

Application Serial No.: 09/926,541  
Amendment dated July 20, 2004  
Reply to Office Action dated October 20, 2003

IN THE CLAIMS

Please amend the claims as follows:

1-15. (Canceled)

16. (Previously Presented) The robot according to claim 27, wherein the holder includes a fastening means in the form of a curved collar.

17. (Previously Presented) The robot according to claim 16, wherein the holder is configured to be fixed by snap action with the curved collar.

18. (Previously Presented) The robot according to claim 16, wherein the holder is configured to be fixed with a hose clamp.

19. (Canceled)

20. (Currently Amended) The robot according to claim ~~27~~ 36, wherein:

the holder and the lid have compatible shapes, and

the holder and the lid cover at least part of the opening when mounted together.

21. (Currently Amended) The robot according to claim ~~27~~ 36, wherein the holder and the lid are configured to cover the opening and to form a tight seal of the opening.

22. (Canceled)

23. (Currently Amended) The robot according to claim ~~27~~ 36, the lid is configured to be divided into sections through at least one direction.

24. (Canceled)

25. (Currently Amended) The process according to claim ~~28~~ 36, wherein at least one of the removable sections of lid is configured to be compatible with the holder, and wherein the holder and the lid are fixed in the opening to cover at least part of the opening.

26. (Previously Presented) The process according to claim 25, wherein the holder and the lid are configured to cover the opening tight-fittingly when mounted together.

27. (Currently Amended) An industrial robot comprising:  
a control system including at least one cable set; and  
a manipulator having an opening and a holder provided within said opening, said holder being detachably fixed along a section of an edge of said opening, said at least one cable set extending through said holder provided within said opening,

~~wherein said manipulator includes a lid configured to be detachably fixed to said edge, said lid having removable sections~~

wherein the manipulator is provided with a pipe socket having the opening.

28. (Currently Amended) A process for fastening in an industrial robot, the robot including a control system having at least one cable set, and a manipulator having an opening and a holder provided within the opening, the at least one cable set extending through the holder, said process comprising the ~~steps~~ step of:

detachably fixing the holder along a section of an edge of the opening, wherein the manipulator is provided with a pipe socket having the opening; and

~~detachably fixing a lid to the edge, wherein the lid has removable sections.~~

29. (Currently Amended) An industrial robot comprising:  
a control system including at least one cable set; and  
a manipulator having an opening and a holder provided within said opening, said holder having a collar with a U-shaped cross section that detachably connects to a section of an edge of said opening, said at least one cable set extending through said holder provided

within said opening,

wherein the manipulator is provided with a pipe socket having the opening.

30. (Canceled)

31. (Previously Presented) The robot according to claim 29, wherein the holder is configured to be fixed with a hose clamp.

32. (Previously Presented) The robot according to claim 29, wherein said manipulator includes a lid configured to be detachably fixed to said edge.

33. (Previously Presented) The robot according to claim 32, wherein said lid has removable sections.

34. (Previously Presented) The robot according to claim 32, wherein:

said holder and said lid have compatible shapes, and

said holder and said lid cover at least part of said opening when mounted together.

35. (Previously Presented) The robot according to claim 32, wherein said holder and said lid are configured to cover said opening and to form a tight seal of said opening.

36. (New) The robot according to claim 27, wherein said manipulator includes a lid configured to be detachably fixed to said edge, said lid having removable sections.

37. (New) The robot according to claim 36, wherein said removable sections are joined together by a frangible notch.

38. (New) The process according to claim 28, wherein said process further comprises the step of detachably fixing a lid to the edge, wherein the lid has removable sections.

39. (New) The process according to claim 38, wherein said removable sections are

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joined together by a frangible notch.

40. (New) The robot according to claim 33, wherein said removable sections are joined together by a frangible notch.